

Investigation:	CERES
Data Product:	Single Scanner Footprint TOA/Surface Fluxes and Clouds (SSF)
Data Set:	Terra (Instruments: CERES-FM1 or CERES-FM2, MODIS)
Data Set Version:	Edition2A

The purpose of this document is to inform users of the accuracy of this data product as determined by the CERES Science Team. The document summarizes user applied revisions (e.g. Rev1), key validation results, provides cautions where users might easily misinterpret the data, provides links to further information about the data product, algorithms, and accuracy, and gives information about planned data improvements. This document also automates registration in order to keep users informed of new validation results, cautions, or improved data sets as they become available.

User applied revisions are a method CERES uses to identify improvements to existing archived data products that are simple for users to implement, and allow correction of data products that would not be possible in the archived versions until the next major reprocessing 1 to 2 years in the future. All revisions applicable to this data set are noted in the section [User Applied Revisions to Current Edition](#).

This document is a high-level summary and represents the minimum information needed by scientific users of this data product. It is strongly suggested that authors, researchers, and reviewers of research papers re-check this document for the latest status before publication of any scientific papers using this data product.

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Nature of the SSF Product

This document discusses the Single Scanner Footprint (SSF) data set version Edition2A for Terra. Additional information is in the [Description/Abstract document](#). The files in this data product contain one hour of full and partial-Earth view measurements or footprints located in colatitude and longitude at a surface reference level.

The Terra SSF is a unique product for studying the role of clouds, aerosols, and radiation in climate. Each CERES footprint (nadir resolution 20-km equivalent diameter) on the SSF includes reflected shortwave (SW), emitted longwave (LW) and window (WN) radiances and top-of-atmosphere (TOA) fluxes from CERES with temporally and spatially coincident imager-based radiances, cloud properties, and aerosols, and meteorological information from a fixed 4-dimensional analysis provided by the Global Modeling and Assimilation Office (GMAO). Cloud properties are inferred from the Moderate-Resolution Imaging Spectroradiometer (MODIS) imager, which flies along with CERES on the [Terra spacecraft](#). MODIS is a 36-channel; 1-km, 500-m, and 250-m nadir resolution; narrowband scanner operating in crosstrack mode. To infer cloud properties, CERES uses a 1-km resolution MODIS radiance subset that has been subsampled to include only the data that corresponds to every fourth 1-km pixel and every second scanline. The Terra SSF retains footprint imager radiance statistics for 5 of the 19 MODIS channels (SSF-115 through SSF-131). The Terra Edition2A SSF contains footprint aerosol parameters from both the 10-km spatial resolution MODIS aerosol product (SSF-132 through SSF-160) and the NOAA/NESDIS algorithm (SSF-73 through SSF-78). Surface fluxes derived from the CERES instrument using several different techniques (algorithms) are also provided. Sampling of the CERES footprints is performed to reduce processing time and data volume. (See [Cautions and Helpful Hints](#).)

CERES defines SW (shortwave or solar) and LW (longwave or thermal infrared) in terms of physical origin, rather than wavelength. We refer to the solar radiation that enters or exits the Earth-atmosphere system as SW. LW is the thermal radiant energy emitted by the Earth-atmosphere system. Emitted radiation that is subsequently scattered is still regarded as LW. Roughly 1% of the incoming SW is at wavelengths greater than 4 μm . Less than 1 W m^{-2} of the OLR is at wavelengths smaller than 4 μm . The CERES unfiltered window (WN) radiance and flux represent emitted thermal radiation over the 8.1 to 11.8 μm wavelength interval.

The SSF product combines the absolute calibration and stability strengths of the broadband CERES radiation data with the high spectral and spatial resolution MODIS imager-based cloud and aerosol properties. A major advantage of the SSF over the traditional ERBE-like ES-8 TOA flux data product is the new angular models derived from CERES Rotating Azimuth Plane data that now allow accurate radiative fluxes not



only for monthly mean regional ensembles (ERBE-like capability) but also as a function of cloud type. Fluxes in the CERES Terra Edition2A SSF are based on a new set of global Angular Distribution Models (ADMS). With these new ADMs, accurate fluxes can be obtained for both optically thin clouds as a class, as well as optically thick clouds. This is a result of new empirical CERES angular models that classify clouds by optical depth, cloud fraction, and water/ice classes. ERBE-like TOA fluxes are only corrected for simple clear, partly-cloudy, mostly-cloudy, and overcast classes. In addition, clear-sky identification and clear-sky fluxes are expected to be much improved over the ERBE-like equivalent, because of the use of the imager cloud mask, as well as the new angular models incorporating ocean wind speed and surface vegetation class.

Finally, early estimates of surface radiative fluxes are given using relatively simple parameterizations applied to the SSF radiation and cloud parameters. These estimates strive for simplicity and as directly as possible use the TOA flux observations. More complex radiative transfer computations of surface and atmosphere fluxes using the SSF data and constrained to the observed SSF TOA fluxes will be provided on the CERES CRS Data Product.

CERES footprints containing one or more MODIS imager pixels are included on the SSF product. Since the MODIS imager can only scan to a maximum viewing zenith angle (VZA) of $\sim 65^\circ$, this means that only CERES footprints with $VZA < 67^\circ$ are retained on the SSF when CERES is in the crosstrack scan mode. When CERES is scanning in either the Rotating Azimuth Plane (RAP) or the alongtrack scan mode, CERES footprints with $VZA > 67^\circ$ do appear on this product, provided they lie within the MODIS swath. Sampling of the CERES footprints is performed to reduce processing time and data volume. (See [Cautions and Helpful Hints](#). The nominal CERES Terra operation cycle for each instrument is 3 months in crosstrack scan mode followed by three months in RAP mode. The cycles of the two instruments are offset by three months such that there is always one instrument operating in the crosstrack scan mode and one in the RAP mode. Nominally, every fourteen days, the instrument operating in RAP mode switches to alongtrack scan mode for one day. In February 2002, the nominal 3-month switching cycle was halted. At that time, the FM1 instrument was placed into crosstrack scan mode, and the FM2 instrument was placed in RAP mode. The instrument scan modes may again change. To determine operations on any given day, refer to the [CERES Operations in Orbit](#).) Users interested in spatially contiguous image data should use the CERES crosstrack data products. Users interested in full angular coverage over time (but with spatial gaps) should use the CERES RAP data. Users interested in many different angular views of the satellite ground track should use the CERES Along Track data.

A full list of parameters on the SSF is contained in the [SSF section of the CERES Data Products Catalog](#) (PDF) and a definition of each parameter is contained in the [SSF Collection Guide](#).

When referring to a CERES data set, please include the satellite name and/or the CERES instrument name, the data set version, and the data product. Multiple files that are identical in all aspects of the filename except for the 6 digit configuration code (see Collection Guide) differ little, if any, scientifically. Users may, therefore, analyze data from the same satellite/instrument, data set version, and data product without regard to configuration code. Depending upon the instrument analyzed, these data sets may be referred to as "CERES Terra FM1 Edition2A SSF" or "CERES Terra FM2 Edition2A SSF."

User Applied Revisions for Current Edition

The purpose of User Applied Revisions is to provide the scientific community early access to algorithm improvements which will be included in the future Editions of the CERES data products. The intent is to provide users simple algorithms along with a description of how and why they should be applied in order to capture the most significant improvements prior to their introduction in the production processing environment. ***It is left to the user to apply a revision to data ordered from the Atmospheric Science Data Center.*** Note: Users should never apply more than one revision. Revisions are independent and the latest, most recent revision to a data set includes all of the identified adjustments.

SSF Edition2A-Rev1

The CERES Science Team has approved a [table of scaling factors](#) which users should apply to the Edition2A SSF SW parameters.

For the CERES SW TOA upward filtered radiance (SSF-32) and the CERES SW TOA upward unfiltered radiance (SSF-35), users should utilize the following equation:

- $\text{radiance}_{\text{rev1}} = \text{radiance}_{\text{orig}} * \text{scaling factor}$

For the CERES SW TOA upward flux (SSF-38), users should utilize the following equation:

- $\text{flux}_{\text{rev1}} = \text{flux}_{\text{orig}} * \text{scaling factor}$

For the CERES SW surface net fluxes, Model A (SSF-44) and Model B (SSF-48), users should utilize the following equation:

- $\text{flux}_{\text{rev1}} = \text{flux}_{\text{orig}} - (\text{SSF-38})_{\text{orig}} * (\text{scaling factor} - 1.0)$

For the CERES SW surface downward fluxes, Model A (SSF-41) and Model B (SSF-46), no corrections should be applied, and thus:

- $\text{flux}_{\text{rev1}} = \text{flux}_{\text{orig}}$

This revision is necessary to account for spectral darkening of the transmissive optics on the CERES SW channels. By June 2005, this darkening has reduced the average global all-sky SW flux measurements by 1.1 and 1.8 percent for Terra FM1 and FM2 data respectively. A complete description of the physics of this darkening appears in the [CERES BDS Quality Summaries](#) under the Expected Reprocessing section. After application of this revision to the Edition2A SSF data set, users should refer to the data as Terra Edition2A-Rev1 SSF.

Cautions and Helpful Hints

There are several cautions the CERES Science Team notes regarding the use of CERES Terra Edition2A SSF data:

General

- Beginning with Terra Edition2A, the SSF contains only every other CERES footprint when the viewing zenith is less than 63°. All footprints with a viewing zenith greater than or equal to 63° are included in the SSF. When SSF-20, "CERES viewing zenith at surface," is less than 63° and SSF-13, "Packet number," is even, then only footprints with an even value in SSF-12, "Scan sample number," are placed on the SSF. When "CERES viewing zenith at surface" is less than 63° and "Packet number" is odd, then only footprints with an odd value in "Scan sample number" are placed on the SSF. (See [SSF Collection Guide](#).) The CERES footprints are sufficiently overlapped in the scanning direction, that this use of every other footprint does not leave gaps in the data spatial coverage, or significantly increase errors in gridded data products or instantaneous comparisons to surface data such as BSRN. All CERES footprints are retained on the ES8 data products.
- CERES footprints in coastline regions generally understate the water percent coverage found in SSF-26, "Surface type percent coverage," and associated with SSF-25, "Surface type index", of 17 (water). The effect is greatest for very jagged coastlines. [View a [detailed discussion](#) (PDF).]
- Before using SSF parameter values, users should check for CERES default values. CERES default values, or fill values, are very large values which vary by data type. (See [SSF Collection Guide](#).) A CERES default value is used when the parameter value is unavailable or considered suspect. SSF-1 through SSF-24 always contain valid parameter values and, therefore, need not be checked for default values. All other parameter values should be checked.
- This SSF contains only CERES footprints with at least one imager pixel of coverage, even if that pixel could not be identified as clear or cloudy. This approach reduces regional biases in fluxes, but it puts more burden on the users to screen footprints according to their needs. For example, if one wants to relate CERES fluxes with imager-derived cloud properties (e.g. cloud fraction), it is very important to check SSF-54, "Imager percent coverage" (i.e., the percentage of the CERES footprint which could be identified as clear or cloudy). When none of the imager pixels within the footprint could be identified as clear or cloudy, the "imager percent coverage" is set to 0 and most imager derived SSF parameters are set to CERES default values. The SSF also contains a new flag that provides information on how much of the footprint contains pixels which could not be identified as clear or cloudy. This flag is referred to as "Unknown cloud-mask" and resides in SSF-64, "Notes on general procedures." Footprints with VZA greater than 80° and less than 100% imager coverage may be partial Earth-view. Consult SSF-34, "Radiance and Mode flags," to determine whether the footprint is full Earth-view or not. When the instrument is in the RAP or alongtrack scan mode, there are more footprints and the SSF files are larger. (See [SSF Collection Guide](#).)
- The geographic location of a CERES flux estimate is at the surface geodetic latitude and longitude of the CERES footprint centroid. On ERBE, all fluxes are located at a geocentric latitude and longitude corresponding to the 30-km level.
- Users interested in surface type should always examine both SSF-25, "Surface type index," and SSF-26, "Surface type percent coverage." (See [SSF Collection Guide](#).)
- Users searching for footprints free of snow and ice should always examine SSF-25, "Surface type index,"; SSF-69, "Cloud-mask snow/ice percent coverage"; and SSF-30, "ADM geo." "ADM geo" is a newly defined parameter which was always set to CERES default in earlier SSF data sets. "ADM geo" provides the PSF-weighted percent coverage of snow and ice over the CERES footprint based on the Clear Sky History albedos. It has a range of 0 - 100 and is never computed within a 50° band of the Equator. When no Clear Sky History albedo snow/ice information is available, for any reason, "ADM geo" is set to CERES default. (See [SSF Collection Guide](#).)
- A footprint is recorded in the hourly SSF file that contains its observation time. However, SSF footprints within the file are ordered on alongtrack angle, SSF-18, and not on time. The alongtrack angle of the satellite is defined to be 0° at the start of the hour. If the instrument is in the RAP or alongtrack scan mode, then footprints can be prior to this start position and yield a negative alongtrack angle.
- Some applications of the SSF data will need to make the distinction between crosstrack, RAP, and alongtrack scan data. Multiple scan modes can occur in the same hour so that bits 8-9 of SSF-34, "Radiance and Mode flags" (see [SSF Collection Guide](#)) should be examined for each footprint to properly identify the scan mode. If actual azimuth angle is required, examine SSF-15, "Clock angle of CERES FOV at satellite wrt inertial velocity."
- Data in an area experiencing a solar eclipse is not processed for the duration of the eclipse. The fraction of SSF data with a solar eclipse is very small: 0.019% in 2000, 0.009% in 2001, 0.047% in 2002, and 0.025% in 2003.
- There is at least one period when the MODIS covers were closed, but CERES continued to process SSF footprints. In cases like this, the SSF parameters which are computed from the imager data are set to default; SSF-53, "Number of imager pixels in CERES FOV" and SSF-54, "Imager percent coverage" are set to 0; and CERES fluxes are computed using neural network derived ADMs. There are footprints where CERES can determine that the scene is clear based on the WN channel brightness temperature. When this happens, the imager pixels within the footprint are assumed to be clear; SSF-54, "Imager percent coverage" is set to 100; SSF-53, "Number of imager pixels in CERES FOV" is non-zero; some imager-based SSF parameters do not contain default values; and the CERES fluxes are computed using clear-sky ADMs. The only known period between the years 2000 and 2002 for which the MODIS covers are



closed but the SSF footprints are processed is from 11:14:29 on April 25, 2000 through 20:45:55 on April 28, 2000. (See [MODIS Instrument Operations Team Event History for AM-1 \(Terra\)](#) or [Terra MODIS Instrument Performance History](#) to determine specifics of MODIS operations, including when MODIS covers were closed.)

Cloud

- For Terra Edition2A SSF, there is no algorithm for mean vertical aspect ratio. Therefore, SSF-111, Mean vertical aspect ratio for cloud layer (see [SSF Collection Guide](#)), should have been set to the CERES default fill value for all footprints. However, due to a software error, SSF-111 contains bogus values which should be ignored by all users.
- There are cases where the cloud properties cannot be determined for an imager pixel that is cloudy at a high confidence level. These pixels are included in the area coverage calculations. The cloud layer areas are proportionately adjusted to reflect the contribution these pixels would have made, but the cloud properties for each layer are not adjusted. The amount of extrapolation can be determined by checking SSF-63, "Cloud property extrapolation over cloud area." (See [SSF Collection Guide](#).)
- Cloud parameters are saved by cloud layer. Up to two cloud layers may be recorded within a CERES footprint. The heights of the layers will vary from one footprint to another. When there is a single layer within the footprint, it is defined as the lower layer, regardless of its height. A second, or upper, layer is defined only when a footprint contains two unique layers. It is possible to have two unique cirrus layers or two unique layers below 4 km. Within an SSF file, the lower layer of one footprint may be much higher than the upper layer of another footprint.
- Night and near-terminator cloud properties - The current method for deriving cloud phase, particle size, and optical depth at night has not been fully tested. It has been implemented primarily to improve the nocturnal determination of cloud effective height for optically thin clouds ($\tau < 5$) and is generally effective at retrieving more accurate cloud heights compared to assuming that all clouds act as blackbody radiators at night. (See [Cloud Properties Accuracy and Validation](#).) Because an accurate optical depth is required to obtain the proper altitude correction, the optical depths for optically thin clouds are considered reasonable.
- Near-terminator cloud amounts - The cloud mask relies heavily on the brightness temperature differences between channels 3 and 4 for identifying clouds at night and in the daytime. The signals differ between night and day for low clouds. At high SZAs ($> 80^\circ$), these signals can cancel each other resulting in low clouds mistaken as clear areas when the cloud temperature is close to or warmer than the clear-sky temperature. Terminator cloud amounts have improved since Edition1A, but can still use further improvement.
- Daytime thin cirrus over land - Comparisons with results from Aqua revealed that thin cirrus clouds were sometimes classified as water clouds due to the use of a 1.6/0.65- μm reflectance ratio test that had only been tested over water. This error is not consistent from day to day. The parameters governing when and where it occurs are yet to be determined. Caution should be used when examining thin clouds over land surfaces. In addition to incorrect phase, the retrievals yield an overestimate of optical depth and underestimate of cloud height. The test is not present in Aqua Edition1B and will be removed in all future Terra Editions.
- Heavy aerosols - Aerosols with relatively large optical depths ($\tau > 1-2$) can sometimes be misidentified as clouds over any surface. Thus, in areas known to experience large dust outbreaks, such as large deserts or adjacent ocean areas, caution should be used when interpreting cloud statistics.
- Optical depths over snow - Cloud optical depth in Edition2A is derived using the SINT when it is known that the underlying surface is either snow or ice-covered. Otherwise, the VISST is used, an approach that often results in an overestimate of the optical depth over snow. In general, the optical depths will be overestimated in snow-covered regions using the Edition 2A algorithm if the underlying surface is not properly classified as being snow-covered.
- Multi-layered/mixed-phase cloud properties - Although an experimental product to detect multi-layered clouds was implemented in Edition2A, its results have not been retained in SSF output because it requires additional study. Thus, all clouds are treated as single phase, single-layer clouds in the retrievals. Mixed phase cloud pixels are interpreted as either entirely liquid or ice clouds depending on the relative amounts of each phase in the top of a particular cloud. Overlapped ice and water cloud pixels will be interpreted in a similar fashion depending on the optical thickness and particle size of the overlying cloud. If it is very thin, the cloud will usually be classified as liquid. Thicker ice clouds over liquid clouds will be classified as ice. The resulting ice particle size for the thicker clouds should be representative of the ice cloud, but will often be too small for the thinner clouds. Mixed phase or overlapped thin-ice-over-thick-water clouds will produce either a liquid water effective radius that is too large for the water droplets in the cloud or too small for the ice crystals in the cloud because the 3.7- μm reflectances for the ice and water particles overlap at the low and high end, respectively. Users will need to use some contextual, temperature, or variability indicators to determine if a particular footprint contains both ice and water clouds if phase index for the footprint is either 1 (water) or 2 (ice). Cloud heights for multi-layered clouds will also be in error if the upper cloud deck is optically thin. The retrieved cloud altitude will be between the height of the lower and the upper clouds.
- "Mean cloud infrared emissivity for cloud layer," SSF-87, is an effective emissivity. Therefore, values greater than 1.0 may occur as a result of IR scattering within the cloud.
- Polar night cloud amounts - The Edition2A algorithm for detecting clouds over regions poleward of 60° at night is still the most uncertain methodology. Missed clouds in those areas can have a significant impact on the computed downwelling longwave flux.
- Sub-polar daytime cloud amounts - After processing of Terra Edition2 clouds began, a coding error was discovered that has a severe



negative impact on the quality of some cloud parameters, primarily amount, in some ocean areas within the latitude bands, 50°N-60°N and 50°S-60°S during their respective summer and autumn periods. The 50°-60° latitude band is the polar transition zone. This error affects ocean and coastal regions only. Pure land regions are unaffected. The error is operative over the Northern Hemisphere roughly between April and October. Conversely, the Southern Hemisphere transition region is affected between October and April. The problem is not significant in most areas, but in the noted regions, the Terra Edition2A data should be used with caution. For a detailed discussion of this error, see [Cloud Properties Accuracy and Validation Sub-polar Daytime Cloud Amounts section](#).

- This SSF includes footprints over hot land and desert for which IR radiances are saturated or otherwise unavailable. The WN brightness temperature is used to identify these scenes. Footprints containing these hot scenes are referred to as "reclassified clear" and flagged in SSF-65, "Notes on cloud algorithms." For "reclassified clear" footprints, most clear footprint area parameters, such as cloud mask percent coverages, and aerosol A parameters, are set to CERES default. Due to a software bug, SSF-79, "imager-based surface skin temperature" is set to the same value as SSF-59, "Surface skin temperature" rather than to CERES default. (See [SSF Collection Guide](#).)

Aerosol

- The Terra Edition2A SSF contains footprint aerosol parameters from both MODIS (SSF-132 through SSF-160) and the NOAA/NESDIS algorithm (SSF-73 through SSF-78). The NOAA/NESDIS parameters provide continuity between the TRMM and Terra SSF data products. The MODIS aerosols are obtained from the [MOD04_L2 product](#), collection 4, which has a 10-km spatial resolution.
- SSF-132, "Percentage of CERES FOV with MODIS land aerosol," and SSF-146, "Percentage of CERES FOV with MODIS ocean aerosol," are incorrectly computed and should not be used. Rough estimates of these percentages can be computed from SSF-134, "PSF-wtd MOD04 aerosol types land," and SSF-148, "PSF-wtd MOD04 solution indices ocean small, average." (See [SSF Collection Guide](#).)
- Two NOAA/NESDIS aerosol optical depth parameters, τ_1 (SSF-73) and τ_2 (SSF-74), have been derived over oceans from MODIS bands centered at $\lambda_1=0.659 \mu\text{m}$ and $\lambda_2=1.640 \mu\text{m}$ using a AVHRR/VIRS-like single channel algorithm. The objective is to provide continuity with the NOAA/AVHRR and TRMM/VIRS analyses, and to check the consistency of the simplistic "NOAA" retrievals against more sophisticated MODIS aerosols (SSF-146 through SSF-160). The user not involved in those activities is advised to use the MODIS aerosol product which is expected to be more accurate. Additionally, the NOAA-like parameters for TERRA have not been validated and thoroughly tested yet. From τ_1 and τ_2 , the Angstrom exponent is estimated as $\alpha = -\ln(\tau_1 / \tau_2) / \ln(\lambda_1 / \lambda_2)$. Note that errors in α change in inverse proportion to τ (Ignatov and Stowe 2000, 2002b).
- There are systematic variations in the NOAA/NESDIS aerosol retrieval which use this algorithm and VIRS or AVHRR imager data. These variations exist with different sun-view angles, precipitable water, wind speed, and infrared radiance (Ignatov and Nalli 2002). Some of the variations are deemed to be artifacts of the retrieval algorithm, and yet some may be real. In particular, variations with wind speed may suggest that ocean specular reflection or white caps may be artificially elevating aerosol optical depth values. Variations with cloud cover may result from either weak cloud contamination (possibly from cirrus cloud, as noted above), or from real changes in aerosol properties due to the clouds (indirect effect). At the time of this writing, no MODIS studies have been done. However, since variations in aerosol retrievals were observed for VIRS and AVHRR, they probably also exist for MODIS.
- NOAA/NESDIS aerosol retrievals (SSF-73 and SSF-74) are reported on the SSF when the solar zenith angle, SSF-21, is less than 70°. For TRMM SSF data sets, which use VIRS imager data, pronounced biases in retrievals start developing for solar zenith angles > 60° (Ignatov and Nalli 2002; Ignatov and Stowe 2002a). At the time of this writing, no MODIS studies have been done. However, it is thought that similar biases may also occur when using MODIS data as input. At this time, use of aerosol retrievals when solar zenith angles exceed 60° is not recommended.
- NOAA/NESDIS visible and near-IR aerosol optical depths (SSF-73 and SSF-74) are retrieved only over ocean. For a discussion of which pixels are used, refer to [Aerosol Properties - Accuracy and Validation](#).

TOA Flux

- During the processing of SSF Edition2A, an error was detected in the SW TOA flux code for CERES FOVs that are cloudy over land and desert. The error is most pronounced for optically thin cloud over bright background surfaces, with instantaneous TOA flux errors reaching 25%. [View a [summary of the error](#) (PDF).] Regional average errors of instantaneous TOA fluxes (at the Terra overpass time) are determined by comparing 1° latitude-longitude averages of fluxes from the Edition2A code ("original") and a corrected version of the code ("corrected"). The regional errors are most pronounced over central Africa, reaching 7 W m⁻² in some 1° regions. The regional average error over all land and desert is approximately 1 W m⁻². In terms of 24-hour average regional errors, these correspond to approximately 2 W m⁻² errors over central Africa and 0.3 W m⁻² for all land and desert surfaces. The global 24-hour average SW flux error due to the code bug is approximately 0.1 - 0.2 W m⁻².
- The CERES Terra angular models (see [TOA Fluxes section](#)) allow determination of accurate TOA fluxes for a wide range of cloud and aerosol conditions. These fluxes will be most accurate when a class of cloud or clear-sky is averaged over a wide range of viewing zenith angles. Not all anisotropy has been removed, and for highest accuracy users are advised to avoid restricting viewing zenith angles to a narrow range (just near nadir for example).
- In sunglint, SSF-38, "CERES SW TOA flux - upwards", is based upon the ADM mean flux corresponding to the observed scene type

rather than the actual radiance-to-flux conversion. This strategy is used to reduce the large anisotropic variability (noise) in the sunglint region, without biasing the large ensemble average fluxes by scene type. To determine whether or not to perform a radiance-to-flux conversion for clear ocean scenes, the standard deviation (σ_{clr}) of the clear ocean ADM anisotropic factors in the vicinity of the measurement (i.e. surrounding w_s , θ_o , θ , and φ bins) must be less than 0.05. When clouds are present, a TOA flux retrieval is performed if $(1-f_{\text{clr}})\sigma_{\text{clr}} < 0.05$. Over sea-ice, a flux retrieval is performed if $(1-f_{\text{ice}})(1-f_{\text{clr}})\sigma_{\text{clr}} < 0.05$. If any of these conditions are not met, the ADM mean flux corresponding to the observed scene type is reported. When CERES is in a crosstrack scan mode, approximately 20-25% of the clear ocean CERES FOVs fail to pass sunglint. The frequency decreases with increasing cloud and sea-ice fraction. Overall 96% of the crosstrack CERES data over ocean passes the sunglint test. For more details, please see p. 69 of "[Radiative Flux Estimation From CERES/Terra Angular Distribution Models](#)" (PDF).

- On Terra Edition 1, TOA fluxes were determined using ADMs developed from CERES on TRMM. Edition 2 CERES TOA fluxes are based on new ADMs developed from Terra measurements. Since the Terra ADMs are defined differently than the TRMM ADMs, the ADM type for inversion (SSF-27 through SSF-29) classification has changed in Edition 2. For a detailed description of the ADM types used in both Edition 1 and Edition 2, please consult [Angular Distribution Models \(ADM\)](#).

Surface Flux

- Users are cautioned about a flaw that was discovered in the SW Model B code that produces SW flux parameters SSF-46 and SSF-48. For certain footprints at high latitudes of the northern hemisphere, especially over Siberia during winter and early spring, the value of column ozone exceeded 500 dobson units, the upper limit prescribed in the code. For those footprints, the values of SSF-46 and SSF-48 could not be computed in the code and default values were recorded in their place. The values of SSF-46 and SSF-48 for the affected footprints are, therefore, missing but they are not erroneous.
- CERES downward LW surface flux - Model B (SSF-47) and CERES net LW surface flux - Model B (SSF-49) were found to be incorrectly computed in a small number of cloudy cases. This happens for those footprints where the cloud amounts are retrieved in one or two layers but corresponding cloud-base heights (Mean cloud base pressure for cloud layer; SSF-101) are not retrieved by the processing system. When this occurs, the system assigns a CERES default value to the cloud-base pressures. The LW Model B then specifies a value for the missing cloud-base pressure of 700 hPa in the single layer case, or 800 hPa for the lower layer or 500 hPa for the upper layer in the two layer case. The incorrect computation occurs in regions of high surface altitude (Altitude of surface above sea level; SSF-24) where surface pressure is less than the above specified cloud-base pressures. This was observed to have occurred in a number of cases over Tibetan region. Users are warned to exercise caution when using LW Model B fluxes over high altitude regions.
- Shortwave Model A and Longwave Model A surface fluxes (SSF-41 through SSF-45) are limited to footprints with clear area coverage (SSF-66) of 99.9% or more. Shortwave Model B and Longwave Model B surface fluxes (SSF-46 through SSF-49), however, are available for all-sky.
- The high latitude and polar surface fluxes from Terra Edition2A have not been validated and should be considered "Beta" quality. (See [Surface Flux Accuracy and Validation](#).)

Accuracy and Validation

Accuracy and validation discussions are organized into sections. Please read those sections which correspond to parameters of interest.

- [Cloud properties](#)
- [Aerosol properties](#)
- [Spatial matching of imager properties and broadband radiation](#)
- [TOA fluxes](#)
- [Surface fluxes](#)

Expected Reprocessing

To correct an error in the SW TOA flux code for CERES footprints that are cloudy over desert or land (see [TOA fluxes accuracy and validation discussion](#)), CERES plans to reprocess the TOA and surface fluxes to produce a Terra Edition2B SSF in the Spring or Summer of 2004.

Additionally, the Terra SSF data product may be reprocessed at a future date, after revision of the algorithms to implement a variety of changes. The time frame for executing a later-edition cloud algorithm is currently expected to occur 2006/2007. Some of the changes that will be included in such a reprocessing are noted below:

- Updated clear-sky maps - Results from Edition2A Clouds will be used to improve the characterization of the clear-sky emittance, temperature, and reflectance fields to provide an improved cloud mask, especially over bright desert areas and over land and desert at night.
- Multi-layered clouds - A new set of methods for identifying multi-layered clouds will be implemented after thorough testing. This change should improve the screening of such data from statistics that assume a single-phase cloud. With further study, it may be possible to separate the properties of the upper layer from those of the lower layer. Mixed phase clouds will be more difficult to identify and quantify.



- More validation statistics - Later algorithm improvements will be guided by results of further validation studies. It is expected that a variety of additional types of comparisons will be conducted including references such as microwave liquid water paths over ocean, radiometer-based optical depths from many surface sites, other ARM sites, and longer time records. More sophisticated field-of-view matching techniques will be used to minimize spatial errors in the comparisons.
- Improved polar clouds and ADMs - The largest errors in the current data sets tend to be for night-time polar cloud properties, and daytime SW ADMs. Improvements are expected in the future.
- Improved separation of elevated thick desert dust layers and clouds.
- Corrections will be developed and applied to remove the bias in the Terra MODIS 3.75- μm channel with the expectation of more accurate cloud particle sizes.

Referencing Data in Journal Articles

The CERES Team has gone to considerable trouble to remove major errors and to verify the quality and accuracy of these data. Please provide a reference to the following paper when you publish scientific results with the data:

Wielicki, B. A., B. R. Barkstrom, E. F. Harrison, R. B. Lee III, G. L. Smith, and J. E. Cooper, 1996: Clouds and the Earth's Radiant Energy System (CERES): An Earth Observing System Experiment, *Bull. Amer. Meteor. Soc.*, 77, 853-868.

When using the cloud data results, please reference the following paper, which will be updated when a journal article becomes available:

Minnis, P., D. F. Young, S. Sun-Mack, P. W. Heck, D. R. Doelling, and Q. Trepte, 2003: "[CERES Cloud Property Retrievals from Imagers on TRMM, Terra, and Aqua](#)" *Proc. SPIE 10th International Symposium on Remote Sensing: Conference on Remote Sensing of Clouds and the Atmosphere VII*, Barcelona, Spain, September 8-12, 37-48.

When data from the Langley Data Center are used in a publication, we request the following acknowledgment be included:

"These data were obtained from the Atmospheric Science Data Center at the NASA Langley Research Center."

The Atmospheric Science Data Center at Langley requests a reprint of any published papers or reports or a brief description of other uses (e.g., posters, oral presentations, etc.) of data that we have distributed. This will help us determine the use of data that we distribute, which is important for optimizing product development. It also helps us to keep our product-related references current.

Feedback and Questions

For questions or comments on the CERES Quality Summary, contact the [User and Data Services](#) staff at the Atmospheric Science Data Center.

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